

```

    CTwoBody
U4 from U3 g p pip n[65] T3 from U4 g p pi0 n[65]
U4 from T3 g p pip n[65] T4 from U4 g p pi0 n[65]
T3 from U3 g p pip n[65] ThetaCM from U3 g p pi0 n[65]
U3 from T3 g p pip n[65] vector_size
T3 from U4 g p pip n[65] vector_size MINUS ONE
T4 from U4 g p pip n[65] fCurrentTagEgyCalibFileName
ThetaCM from U3 g p pi0 n[65]
U4 from U3 g p pi0 n[65] fMaxU3
T3 from U3 g p pi0 n[65] fMaxU4
U3 from T3 g p pi0 n[65] fMaxT4
T3 from U4 g p pi0 n[65] fMaxP3
T4 from U4 g p pi0 n[65] fMaxP4
ThetaCM from U3 g p pi0 n[65] fMinNumberOfTestGraphs
U4 from U3 g p pi0 n[65] fPart[4]
U4 from T3 g p pi0 n[65] testGraph[12]
T3 from U3 g p pi0 n[65] fIsA
U3 from T3 g p pi0 n[65] fIsA

@~CTwoBody
CTwoBody
Init
Test
GenerateKinematics
GetU4_from_U3_g_p_pip_n
GetU4_from_U3_g_p_pi0_n
GetU4_from_T3_g_p_pip_n
GetU4_from_T3_g_p_pi0_n
GetU3_from_T3_g_p_pip_n
GetU3_from_T3_g_p_pi0_n
GetT3_from_U4_g_p_pip_n
GetT3_from_U4_g_p_pi0_n
GetU4_from_U4_g_p_pip_n
GetU4_from_U4_g_p_pi0_n
GetP3_from_U3_g_p_pip_n
GetP3_from_U3_g_p_pi0_n
GetThetaCM_from_U3_g_p_pip_n
GetThetaCM_from_U3_g_p_pi0_n
GetThetaCM_from_U4_g_p_pip_n
GetThetaCM_from_U4_g_p_pi0_n
GetU4_from_ThetaCM_g_p_pip_n
GetU4_from_ThetaCM_g_p_pi0_n
GetU4_from_U3_g_p_pip_n
GetU4_from_U3_g_p_pi0_n
GetU4_from_T3_g_p_pip_n
GetU4_from_T3_g_p_pi0_n
GetU3_from_U4_g_p_pip_n
GetU3_from_U4_g_p_pi0_n
GetT3_from_ThetaCM_g_p_pip_n
GetT3_from_ThetaCM_g_p_pi0_n
GetP3_from_U3_g_p_pip_n
GetP3_from_U3_g_p_pi0_n
GetThetaCM_from_U3_g_p_pip_n
GetThetaCM_from_U3_g_p_pi0_n
GetThetaCM_from_U4_g_p_pip_n
GetThetaCM_from_U4_g_p_pi0_n
GetU4_from_ThetaACM_g_p_pip_n
GetU4_from_ThetaACM_g_p_pi0_n
GetU4_from_U4_g_p_pip_n
GetU4_from_U4_g_p_pi0_n
GetP4_from_U4_g_p_pip_n
GetP4_from_U4_g_p_pi0_n

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